



INTERACTIVE DEFORMATION THROUGH MESH-FREE STRESS ANALYSIS IN VIRTUAL REALITY

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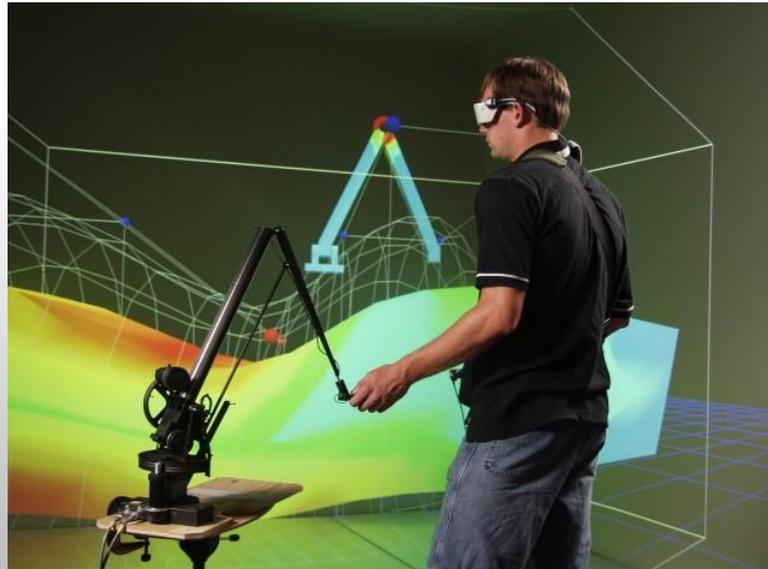
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Program Director
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National Science Foundation



Interactive Shape Manipulation in VR

- Interaction with geometry
- Analysis tied with CAD and shape deformation
- Easier identification of problematic stresses in early design
- Faster product development
- Collaborative design





Virtual Reality Environment

- Developed for C4 and C6 at VRAC, Iowa State
- Can run on desktop, single wall screen
- Renovated C6:
 - 4000x4000 pixel resolution per wall
 - 48 dual-CPU workstations
 - 24 Sony SRX-S105 digital cinema projectors
- SensAble Technology Phantom haptic device

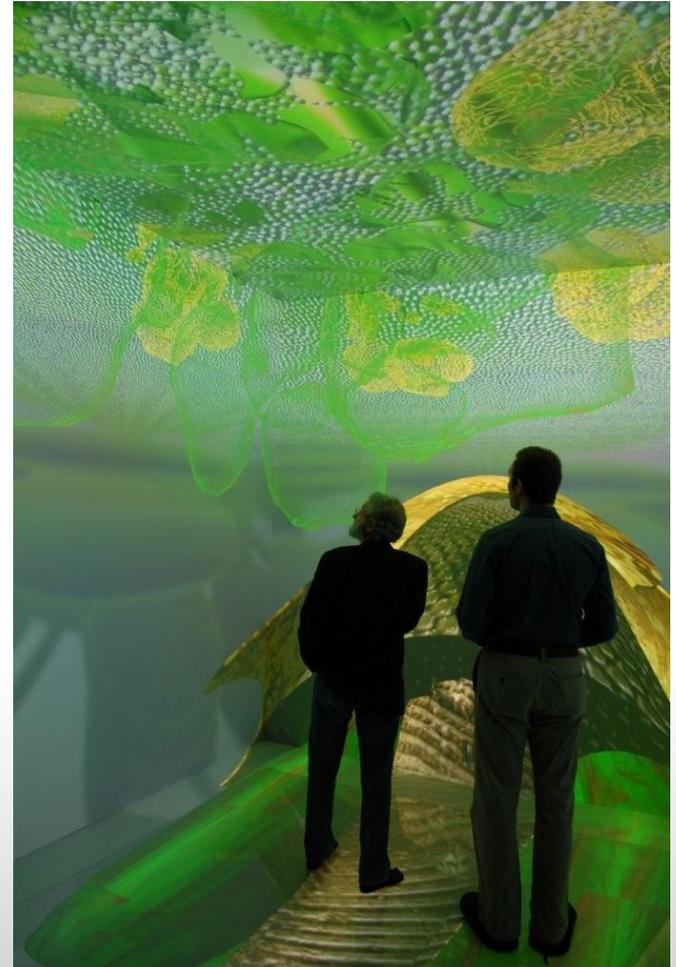
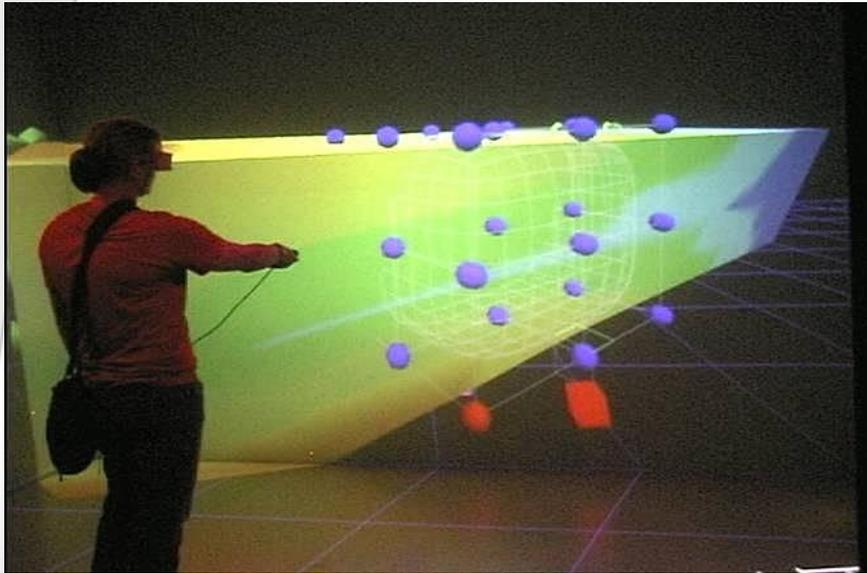


Image courtesy of the Meta!Blast project, Iowa State University. Funded in part by NSF grants IOB-0219366 and DBI-0520267; ISU College of Liberal Arts and Science.”

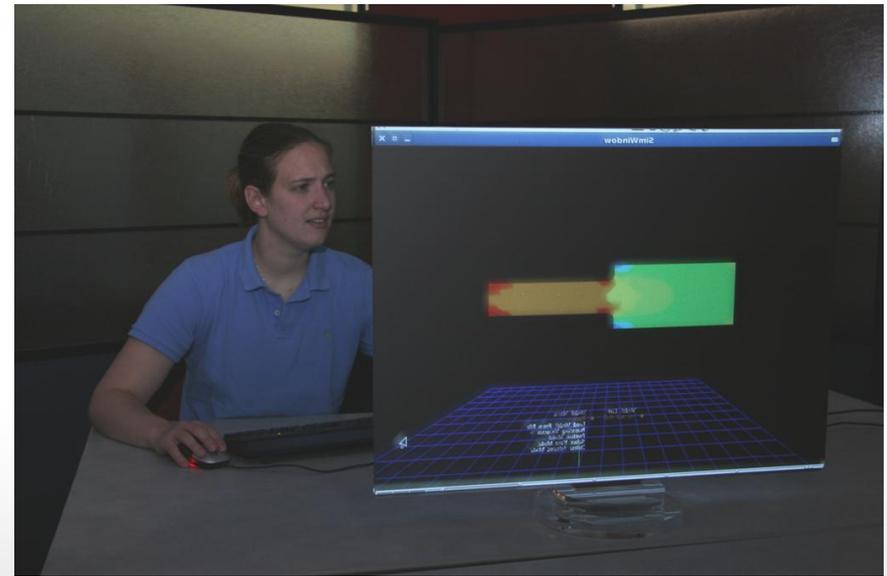


IVDA Virtual Environments

- Immersive



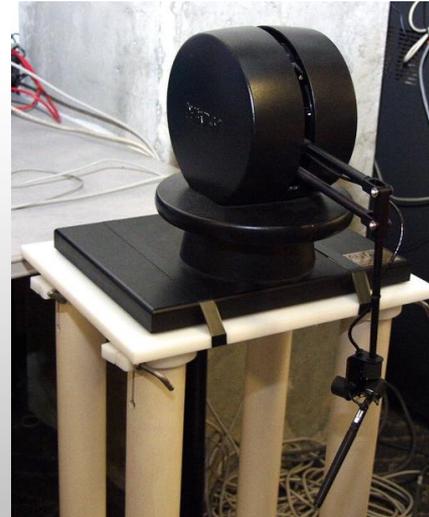
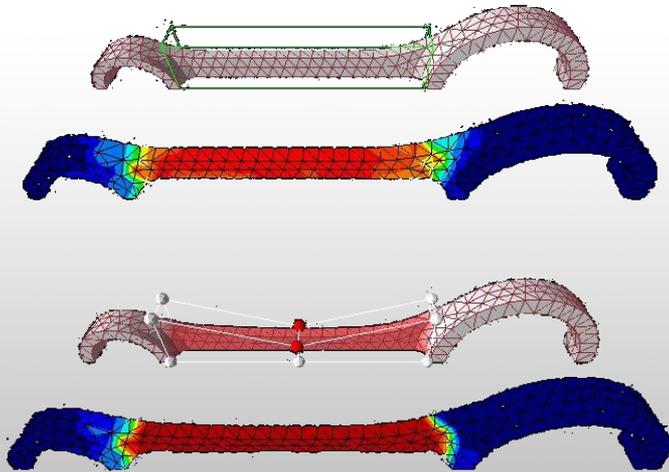
- Desktop





Background

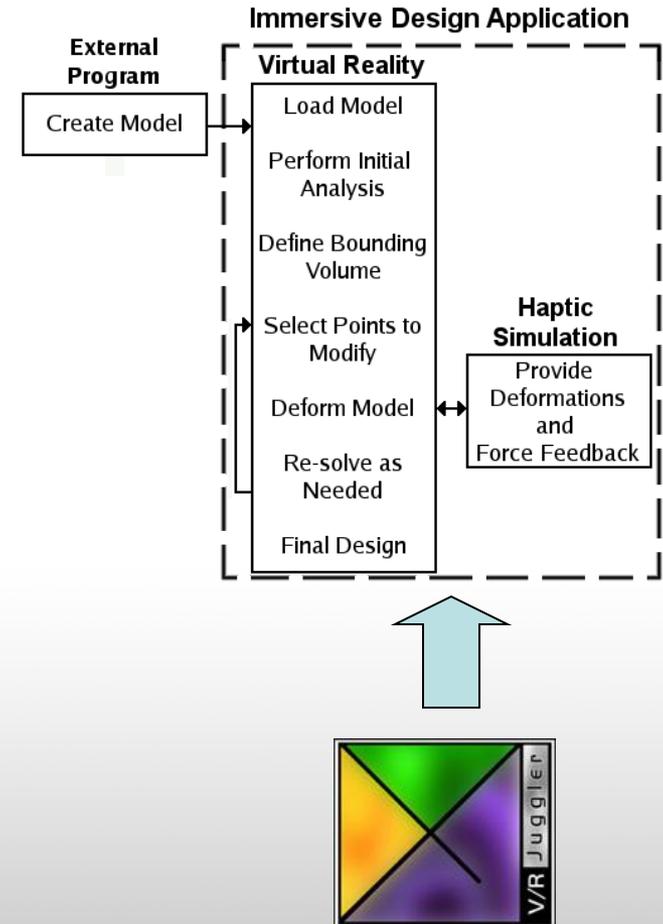
- Yeh and Vance, 1998: linear Taylor series approximations based on pre-computed stress sensitivities and NURBS bounding volume to deform part shape
- Chipperfield et al., 2006 : Mesh-free and PCG re-analysis method to accurately re-compute stress
- Fischer et al., 2007: haptic device implementation





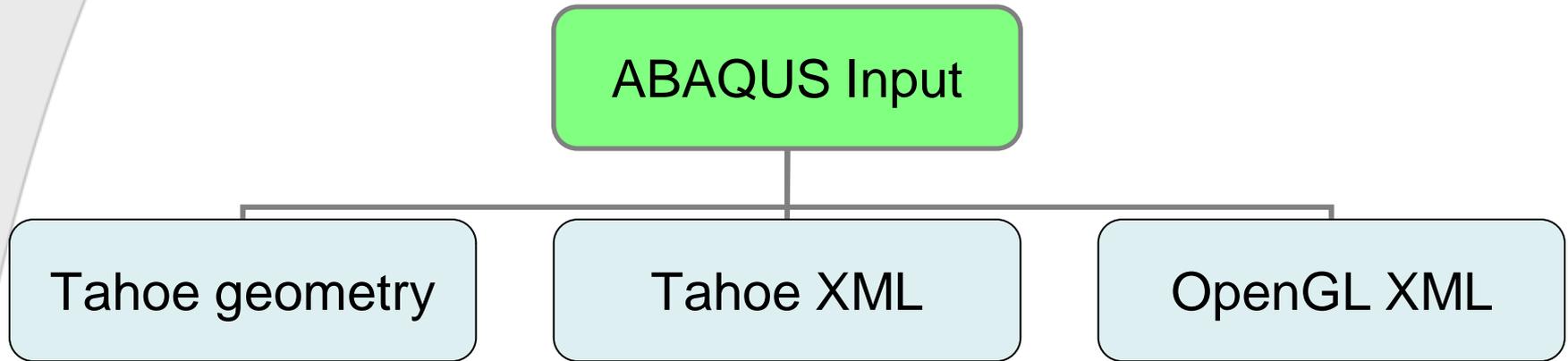
Software

- IVDA
 - C++ programming language
 - VR Juggler software toolkit
 - OpenGL
 - OpenHaptics toolkit for Phantom haptic device
 - OPCODE (Optimized Collision detection)
 - Tahoe OpenSource toolkit (<http://tahoe.ca.sandia.gov/>)
- External:
 - ABAQUS





File Converter (ABAQUS - Tahoe)



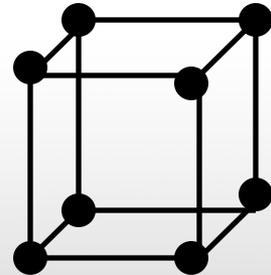
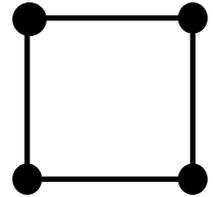
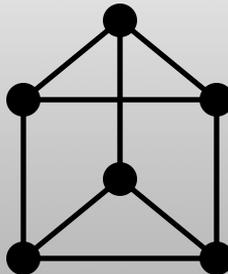
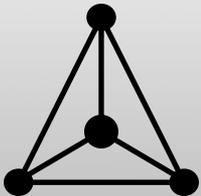
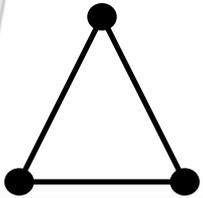
IVDA





Element Definitions

ABAQUS Geometry	Tahoe Geometry	Dimensions	# of Nodes
-	point	1	1
T2D2	line	1	2
CPS4	quadrilateral	2	4, 8
CPS3	triangle	2	3
C3D8	hexahedron	3	8
C3D4	tetrahedron	3	4
C3D6	pentahedron	3	6





Abaqus

** PARTS

** ASSEMBLY

Element, type=CPS4

1, 1, 15, 123, 57

2, 15, 2, 124, 123

3, 2, 16, 125, 124

*Node

1, 210., 25.

2, 209.020569, 5.50202799

3, 210., -25.

** MATERIALS

** BOUNDARY CONDITIONS

** LOADS



Tahoe geometry file

*dimensions

349 # num nodes

2 # num spatial dimensions

1 # num element sets

[ID] [nel] [nen] 1 297 42

num node sets

[ID] [nnd]

1 112 6

*elements

*set

297 # num elements

4 # num nodes/element

1 1 15 123 57

2 15 2 124 123

3 2 16 125 124

*nodes

349 # num nodes

2 # num spatial dimensions

1 210 25

2 209.021 5.50203

3 210 -25



Tahoe XML

```
<nodes>
</dof_labels>
  <kinematic_BC dof="1" node_ID="1" />
  <kinematic_BC dof="2" node_ID="1" />
  <force_BC dof="1" node_ID="2" schedule="1" value="1000"/>
</field>
</nodes>
<element_list>
  <small_strain_meshfree field_name="displacement">
    <quadrilateral num_ip="4"/>
    <solid_element_nodal_output principal_stress="1"/>
    <small_strain_element_block>
      <block_ID_list>
        <String value="1"/>
      </block_ID_list>
      <small_strain_material_2D>
        <small_strain_StVenant_2D density="1.0">
          <E_and_nu Poisson_ratio="0.35" Young_modulus="1e+08"/>
        </small_strain_StVenant_2D>
      </small_strain_material_2D>
    </small_strain_element_block>
  <meshfree_support_2D>
    <RKPM>
      <cubic_spline_window support_scaling="1.51"/>
    </RKPM>
  </meshfree_support_2D>
  <meshfree_fracture_support/>
</small_strain_meshfree>
```

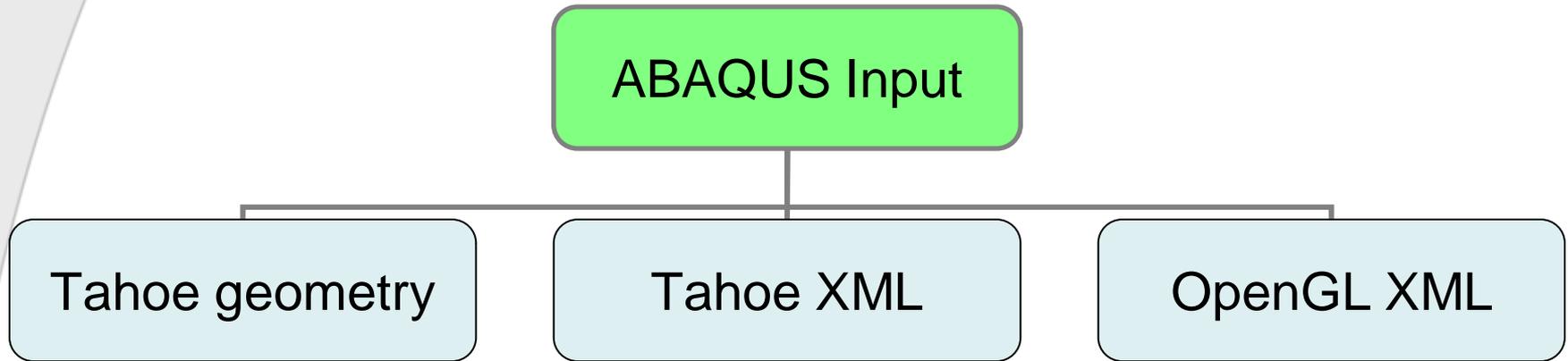


OpenGL XML

```
<model format="XML From ConvertBase">  
<geometry num_nodes="349" num_elements="297">  
<node id="0">210,25,0</node>  
<node id="1">209.021,5.50203,0</node>  
<node id="2">210,-25,0</node>  
<node id="3">400,-25,0</node>  
<elem id="0" type="CPS4">0,14,122,56</elem>  
<elem id="1" type="CPS4">14,1,123,122</elem>  
<elem id="2" type="CPS4">1,15,124,123</elem>  
<elem id="3" type="CPS4">15,16,125,124</elem>
```



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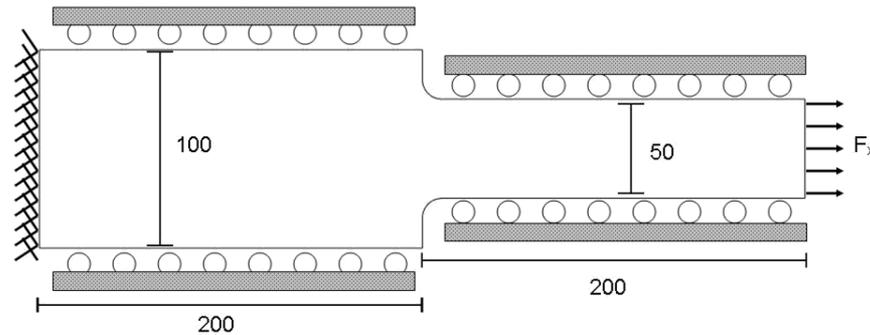
IVDA



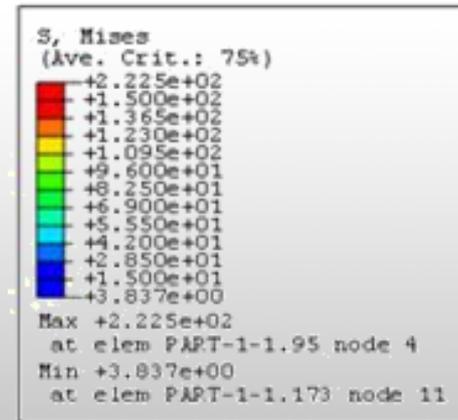
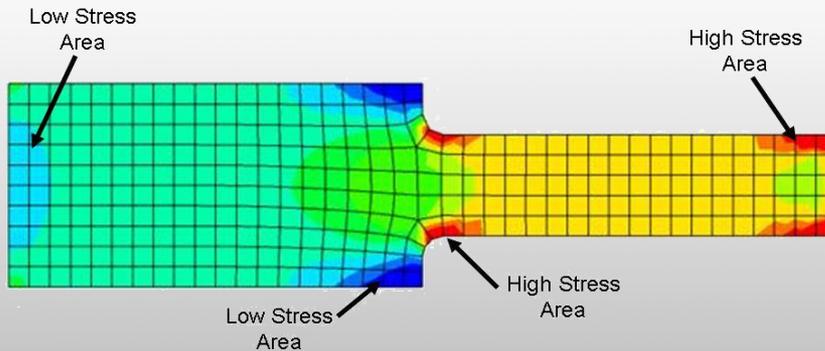


2D Analysis Example

- Stepped beam example

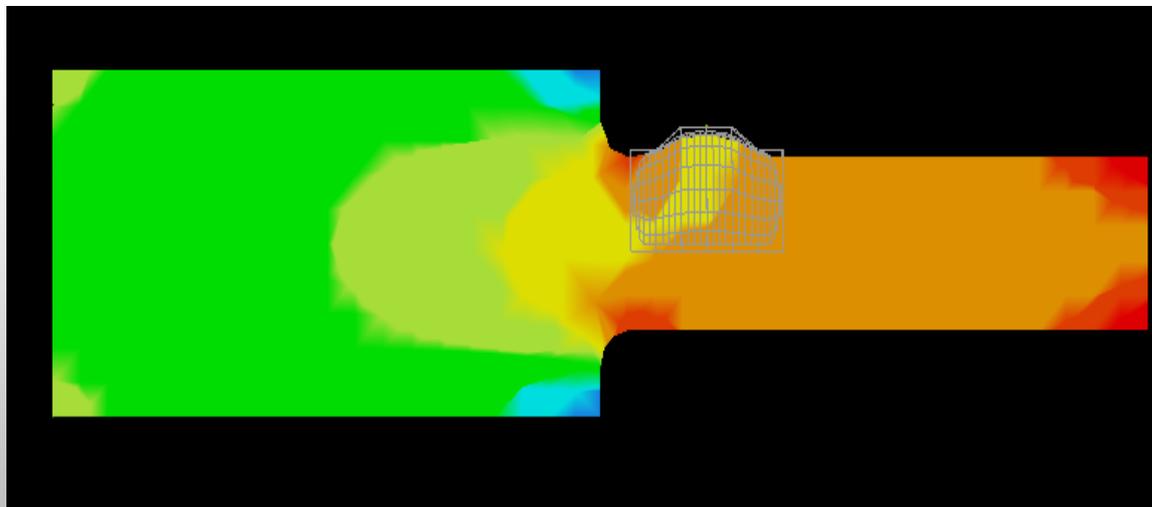
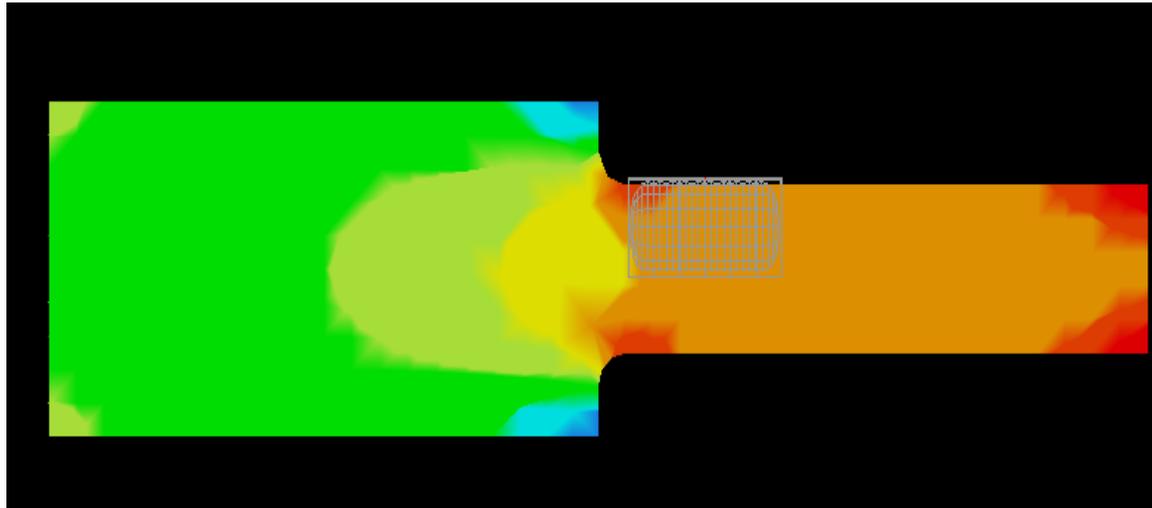


- ABAQUS mesh





IVDA Results





Conclusion

- Investigation of shape through interactive design coupled with mesh-free analysis
- Able to perform mesh-free analysis
 - 2D, 3D elements
- Able to deform model with stress updates
- Able to assemble parts during deformation
- During assembly operations, collision detection prevents interpenetration



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Questions?

IVDA

Mesh-Free Design
In VR